

Graph Inference with Distance Queries

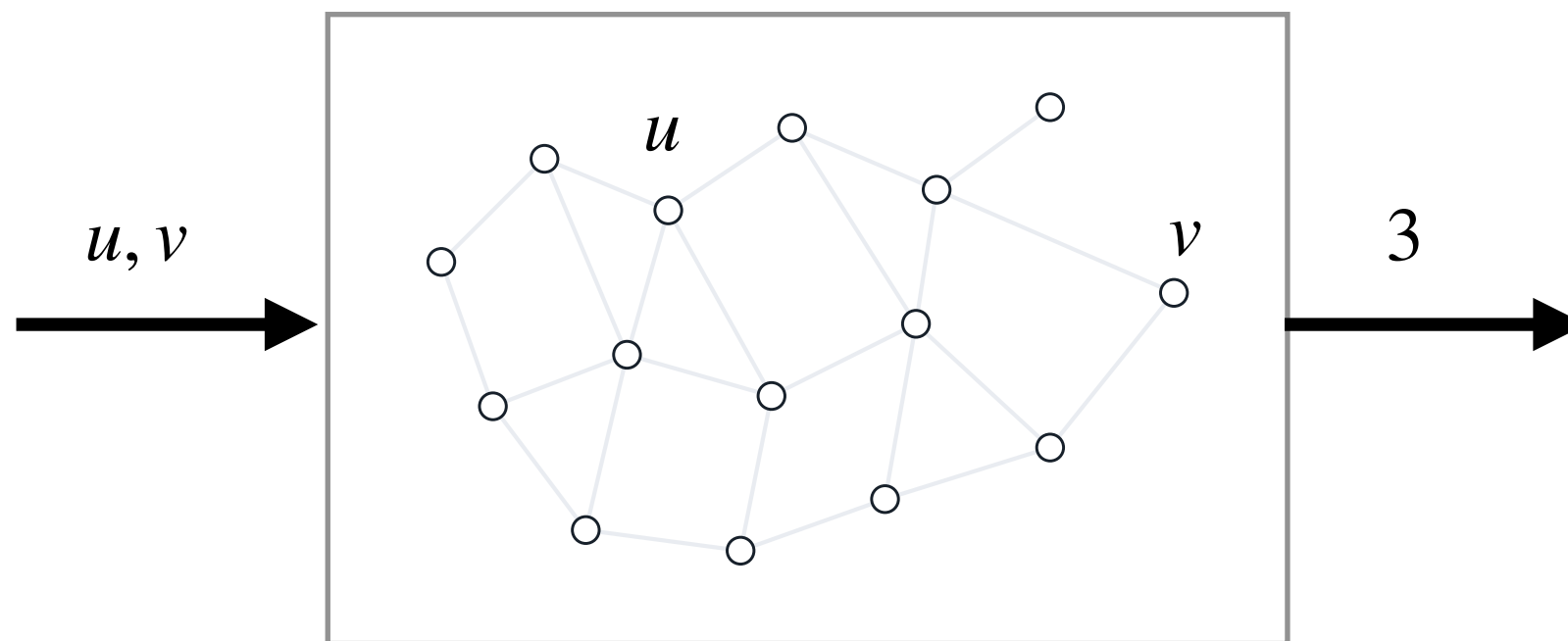
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Oregon State University

Joint work with Mitchell Black, Huck Bennett, Chirag Kaudan, Evelyn Warton

Graph Reconstruction with Distance Queries

- Given:
 - Graph $G = (V, E)$, with known vertices and hidden edges
 - Graph Distance Oracle: Given $u, v \in V$, returns $d(u, v)$



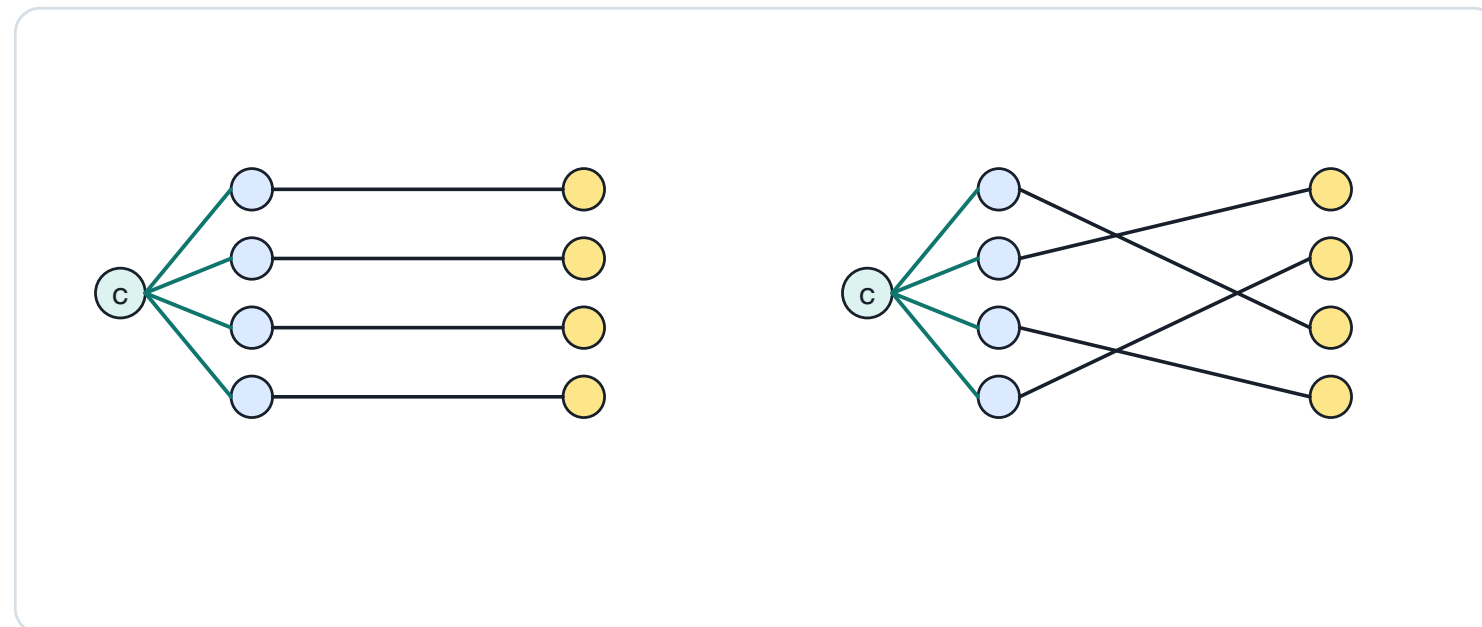
- **Problem:** How many distance queries we need to reconstruct G ?

$O(n^2)$ Upper Bound for Reconstruction

- Check for and edge between every pair of vertices
 - There is an edge iff the shortest path length is one

$\Omega(n^2)$ Lower Bounds

- Extremely sparse (disconnected) graphs; e.g. a single edge [Reyzin Srivastava 07]
- Trees with high-degree [Reyzin Srivastava 07]
 - Hard to reconstruct a subdivided star even with fixed center, first layer and second layer. (reduction from learning matchings with edge detection queries [Alon Beigel Kasif Rudich Sudakov 04])



Subquadratic Reconstruction with SP queries

- Bounded degree trees and tree-like graphs: $O(n \log n)$ queries
- Bounded bfs-width graphs
 - Bounded bandwidth: $n \log^{O(1)} n$ queries
 - Bounded degree bounded pathwidth: $O(n^{2-\epsilon})$
- General bounded degree graphs: $\widetilde{O}(n^{3/2})$ -queries with high prob.

Subquadratic Reconstruction with SP queries

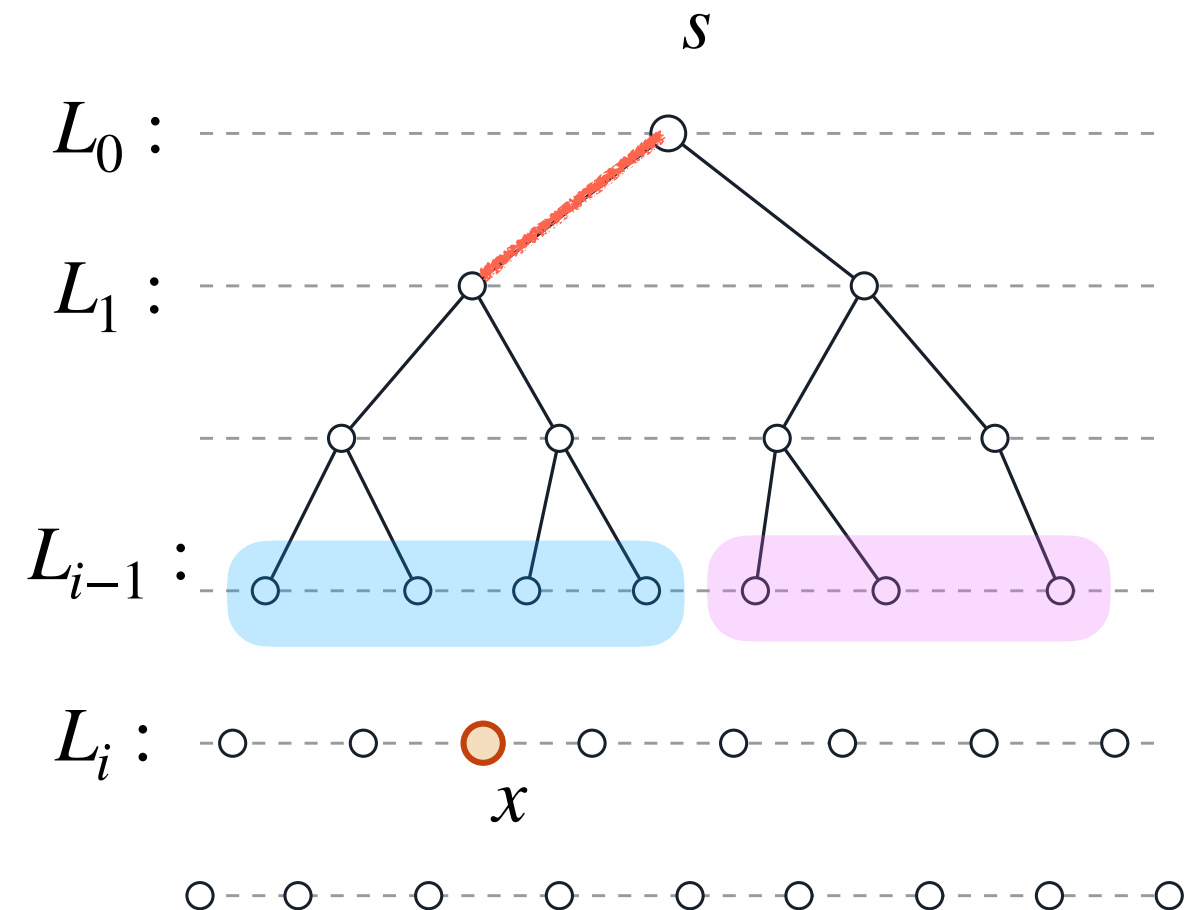
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Bounded degree trees — $\Theta(n \log n)$

- Pick a root $s \in V$
- Build bfs layers from s ($n - 1$ queries)
- Traverse vertices layer by layer
- Find the parent of each vertex:
 - Use tree balanced separator to binary search among L_{i-1}
($O(\log n)$ queries per vertex)

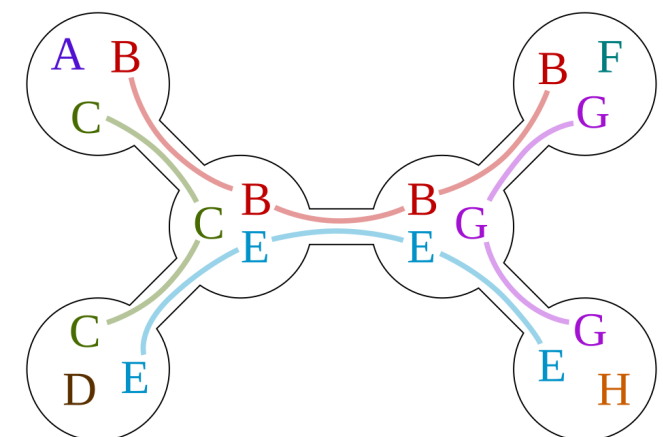
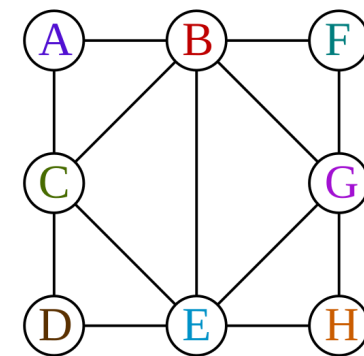


[Hein 89, Bestide Groenland 24]

Tree decomposition, length and width

Tree decomposition of $G = (V, E)$: bags of vertices in V arranged on a tree T such that

- Each vertex is contained in a non-empty connected subtree of T
- Each edge is contained in at least one bag
- Length of a decomposition: the max diam of its bags
 - **Treelength**: min length over all tree decompositions
- Width of a decomposition: the max size of its bags (minus one)
 - **Treewidth**: min width over all tree decompositions



Tree decomposition, length and width

Treelength and treewidth are very different parameters:

- K_n has treelength 1 and treewidth $n - 1$
- C_n has treelength $n/3$ and treewidth 2

Useful intuition: A graph has bounded treelength if and only if its shortest-path metric embeds into a tree metric with bounded additive distortion [Berger Seymour 24]

Tree-like graphs

Bounded degree bounded treelength graphs can be reconstructed (deterministically) with $O(n \log n)$ shortest paths queries [Kaudan N '25]

- **Intuition:** If I know the graph up to layer i I can approximate optimal decomposition use to layer $i - \delta$ with $\delta = O(1)$.

To find parents of vertices in L_i

- Binary search on partially build decomposition up to layer $i - \delta$
- Exhaustive search on the remaining candidates

Tree-like graphs

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- chordal $\subseteq k$ -chordal $\subseteq$ bounded treelength
 - Sequence of work on graph reconstruction with SP queries for these families [Kannan Mathieu Zhou 2018][Rong Li Yang Wang 2021][Bestide Groenland 24a] [Bestide Groenland 24a]

Open: What about bounded degree bounded treewidth graphs?

Subquadratic Reconstruction with SP queries

- Bounded degree trees and tree-like graphs: $O(n \log n)$ queries
- **Bounded bfs-width graphs**
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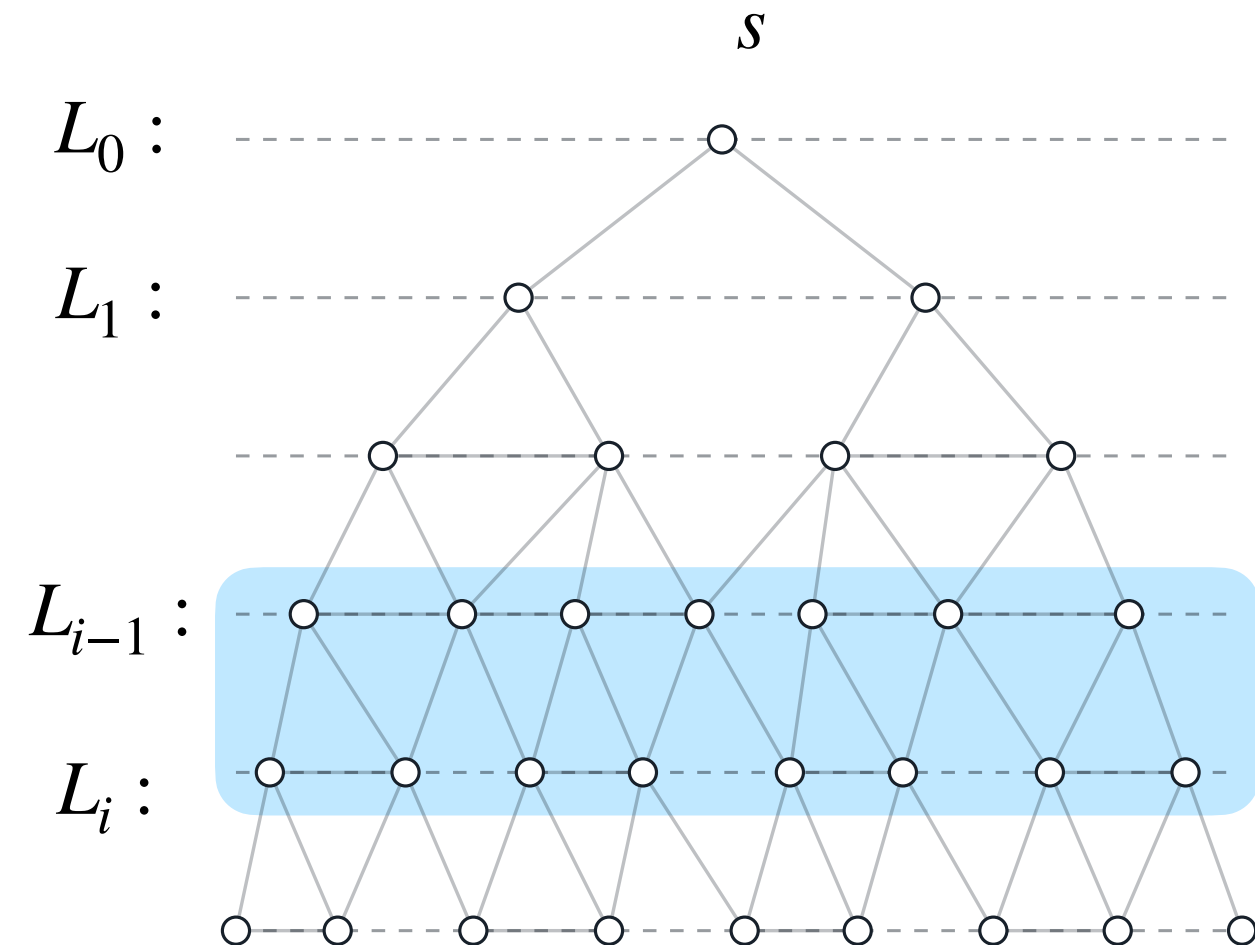
Graphs with bounded bfs-width

Simpler Algorithm:

- Pick a root $s \in V$
- Build bfs layers ($n - 1$ queries)
- Check all “potential” edges;
edges with endpoints in some

$$S_i = L_{i-1} \cup L_i$$

- **Query complexity:** $O(bn)$, b
widest bfs layer



Graphs with bounded bfs-width

- Bounded bandwidth graphs have bfs-width $\log^{O(1)} n$ [Eppstein Goodrich Liu 25] $\Rightarrow O(n \log^{O(1)} n)$ reconstruction algorithm
- Bounded degree bounded pathwidth graphs have bfs-width $n^{1-\varepsilon}$ [Kaudan N 26] $\Rightarrow O(n^{2-\varepsilon})$ reconstruction algorithm.

Open: What about bounded degree bounded treewidth graphs?

Subquadratic Reconstruction with SP queries

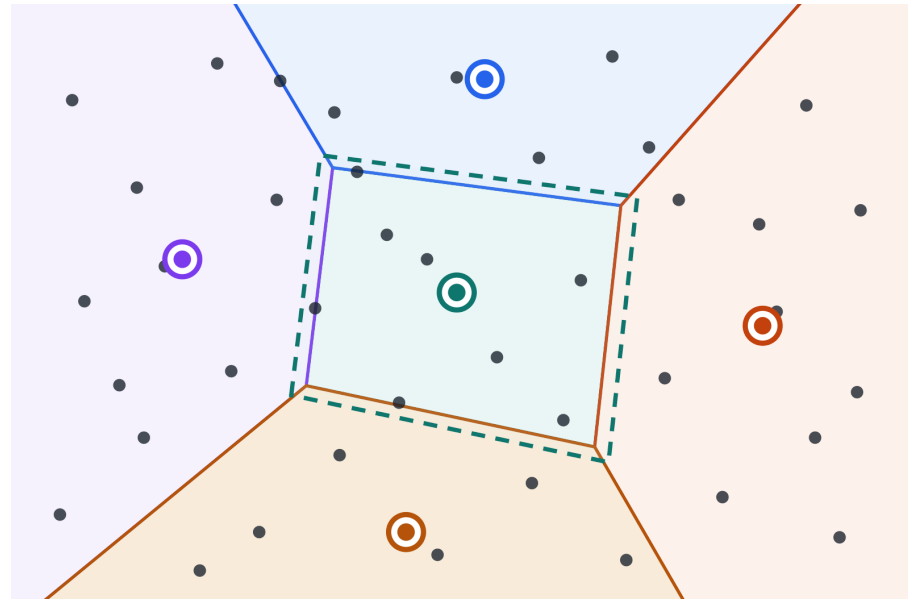
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- **General bounded degree graphs: $\widetilde{O}(n^{3/2})$ -queries with high prob.**

Bounded degree graphs – $\widetilde{O}(n^{3/2})$

- Abstract algorithm:
 - Build a covering of edges, $S_1, \dots, S_k \subseteq V$,
 - Each edge has its both endpoints in at least one of S_i 's
 - For example: S_i 's can be consecutive pairs of bfs layers
 - Reconstruct the induced graph of each S_i with brute force, in quadratic time
- Reconstruction time: $\sum |S_i|^2$
- A covering with $k = \widetilde{O}(\sqrt{n})$ and $|S_i| = O(\sqrt{n})$ can be computed with $\widetilde{O}(n^{3/2})$ queries for bounded degree graphs $\Rightarrow$ Total $\widetilde{O}(n^{3/2})$ query complexity [Kannan Mathieu Zhou 18]

Building the covering [Kannan Mathieu Zhou '18]

- $S_1, \dots, S_k$ are extended Voronoi cells of a set A of “landmarks”.

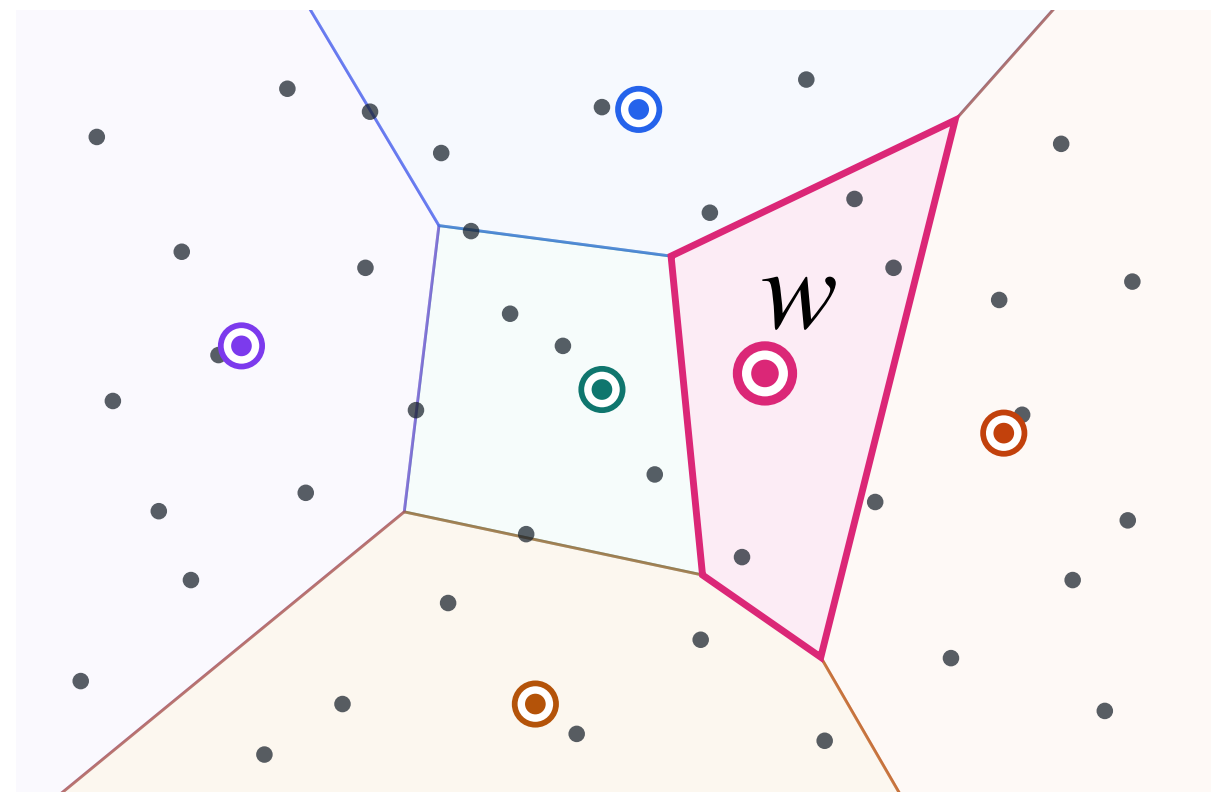


- Extended Voronoi cells: include into each Voronoi cell its one hop neighbors
- $\Rightarrow$ all edges are covered

Building the covering [Kannan Mathieu Zhou 18]

- A is computed via rounds of sampling
 - $W \subseteq V$: is the set of vertices w with “large clusters”
 - $|\{u \in V \mid d(u, w) < d(u, A)\}| > \sqrt{n}$
 - The Voronoi cell of w in the Voronoi diagram of $\{w\} \cup A$ is large ($> \sqrt{n}$)
 - Add each $w \in W$ to A with probability $\sim 1/\sqrt{n}$

Similar to [Thorup Zwick 01]



Reconstruction with shortest path queries:

Number of Queries

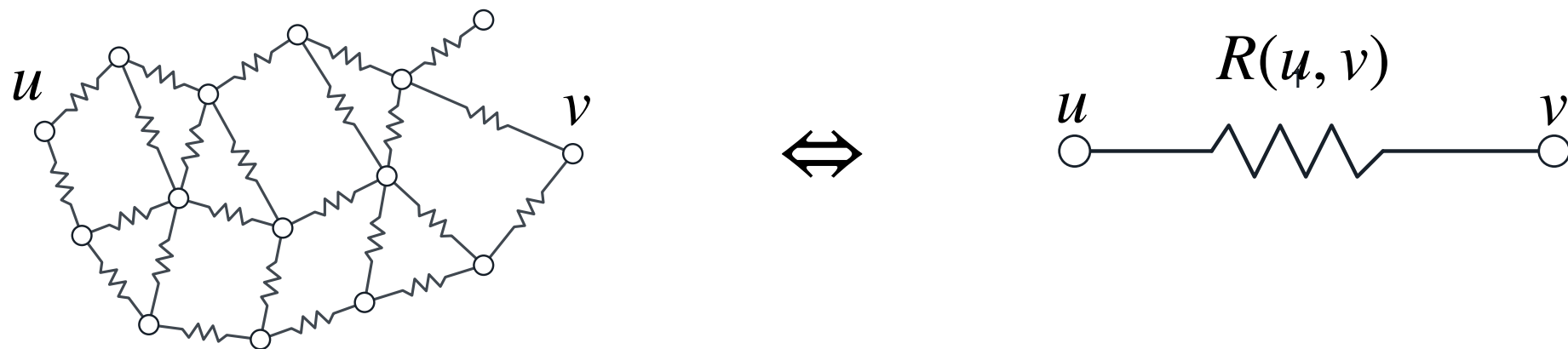
General	$\Theta(n^2)$
Bounded deg bounded treelength	$\Theta(n \log n)$
Bounded bandwidth	$n \log^{O(1)} n$
Bounded deg bounded pathwidth (~bounded cutwidth)	$O(n^{2-\varepsilon})$
Bounded deg (randomized)	$O(n^{3/2})$

Shortest path vs. effective resistance queries:

	Number of SP Queries	Number of ER queries
General	$\Theta(n^2)$	$\Theta(n^2)$
Bounded deg bounded treelength	$\Theta(n \log n)$	?
Bounded bandwidth	$n \log^{O(1)} n$	?
Bounded deg bounded pathwidth (~bounded cutwidth)	$O(n^{2-\varepsilon})$	?
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Effective resistance

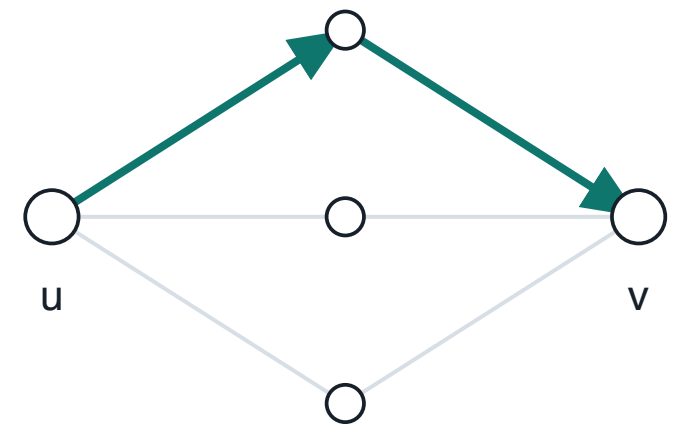
- Effective resistance distance, $R(u, v)$
 - The resistance of the equivalent one-resistor network for u, v



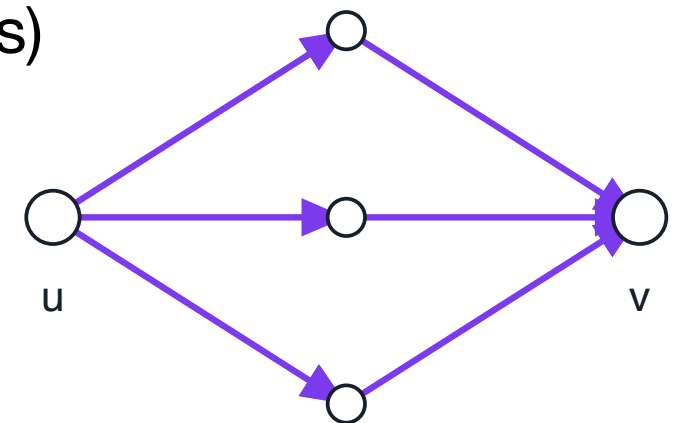
- $R(u, v) = \frac{C_{u,v}}{2m}$, $C_{u,v}$: commute time between u, v (expected time for a random walk starting at u to visit v and come)
- $R(u, v) = (e_u - e_v)^T L_G^+ (e_u - e_v)$, $L_G = D_G - A_G$ is Laplacian of G

SP and ER, flow interpretation

- Shortest path distance
 - $d(u, v)$: Minimum ℓ_1 -value of a u to v unit flow
 - $d(u, v) = \min \|f\|_1$ (f ranges over u to v unit flows)



- Effective resistance distance,
 - $R(u, v)$: Minimum squared ℓ_2 -value of a u to v flow
 - $R(u, v) = \min \|f\|_2^2$ (f ranges over u to v unit flows)



$\Theta(n^2)$ ER queries for general graphs

- $O(n^2)$ -query algorithm [Spielman 12, Hoskin Musco Musco Tsourakakis 18]
 - Interesting formula: $L^+ = -\frac{1}{2}\Pi R \Pi$
 - $\Pi = I - \frac{1}{n} \cdot \mathbf{1}\mathbf{1}^T$ (Project away from all 1 vector, the kernel of Laplacian)
 - R : The matrix of all pairwise effective resistances
- $\Omega(n^2)$ lower bound is implied by shortest path lower bounds
 - ER and SP are the same on acyclic graphs

Big Open question:

Which graph families beyond bounded degree trees admit reconstruction with a subquadratic number of ER queries?

- Testing some properties is possible with linear ER queries
- Graph completion is possible with linear queries: given a graph with k missing adjacency matrix queries, we can complete it with k ER queries

[Black Bennett N Warton '26]

What is missing compared to shortest paths?

Methods for finding the covering set

- No bfs-layer property
- No obvious ER analogue of the Voronoi covering construction

Methods to reconstruct an induced subgraph using number of queries proportional to its size:

- In particular, no obvious way to check if there is an edge between two vertices quickly
- In fact, a linear lower bound for this task!

Discovering the neighbors of a vertex

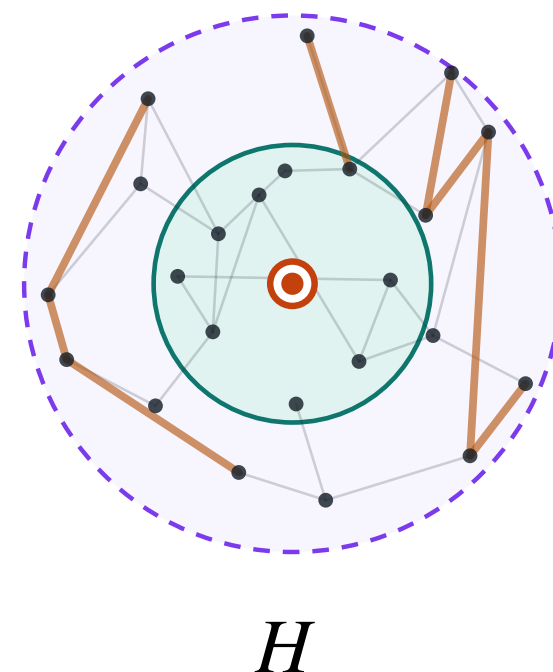
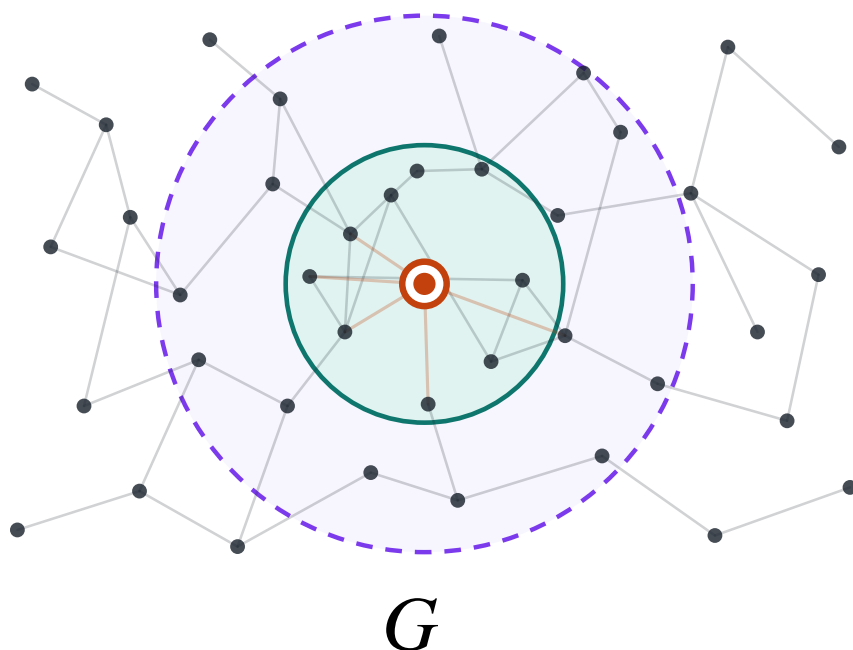
The neighbors of a vertex v can be found with $n - 1 + |B_R(v,2)|^2$ ER queries.

- $B_R(v,2)$ is the set of all vertices that are at ER distance at most 2 from v .



Discovering the neighbors of a vertex

- Algorithm:
 - ER-query all vertices from v to compute $B_R(v,2)$
 - ER-query all pairs within $B_R(v,2)$
 - Reconstruct the **weighted** graph H on $B_R(v,2)$ that realize ER values between these vertices in G (using $|B_R(v,2)|^2$ ER queries)
 - H : Schur complement of G onto $B_R(v,2)$
 - Return neighbors of v in H



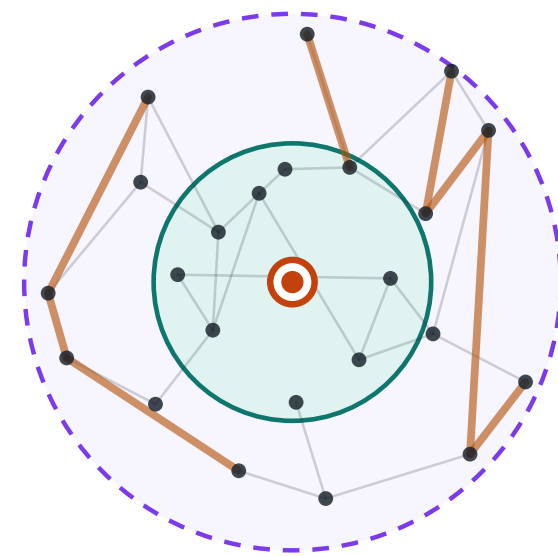
Discovering the neighbors of a vertex

Neighbors of v in H and G are identical

- $uv \in E \Rightarrow R(u, v) \leq 1$
- Algorithm to build Schur complement onto $S \subseteq V$:
 - Iteratively, eliminate every vertex $v \in V \setminus S$ by replacing it with a clique on its neighbors (with appropriate weights)
- The process does not change the weight of an edge that entirely in the smaller ball $B(v, 1)$, as outside vertices don't have neighbors in the smaller ball
- All neighbors x of v are in $B(v, 1)$; $R(v, x) \leq 1$



G



H

How dense is ER space?

The neighbors of a vertex v can be found with $n - 1 + |B_R(v, 2)|^2$ ER queries.

- How large is $B_R(v, 2)$?
 - As large as the entire graph (expanders)
 - Constant size for bounded deg bounded treewidth and bounded deg planar graphs
- **Implication:** Property testers with $f(\epsilon, n)$ queries in bounded degree model can be simulated with $n \cdot f(\epsilon, n)$ ER queries in bounded treewidth and planar graphs. Examples: k -connectivity, bipartiteness, presence of long cycles

Thanks/Open Problems!

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